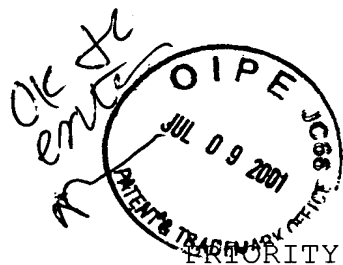


Patent Application of J.J. Richardson, Steve Stone and Donald

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#9



SENSING DEVICE FOR MONITORING CONDITIONS
AT A REMOTE LOCATION AND METHOD THEREFOR

[0001] This is a nonprovisional application of provisional patent application Ser. No. 60/113466, filed December 23, 1998.

INCORPORATION BY REFERENCE

[0002] The MICROFICHE APPENDIX that is attached hereto for the software program submission is incorporated by reference herein.

5 The MICROFICHE APPENDIX includes a page of microfiche containing 35 frames.

FIELD OF THE INVENTION

[0003] The present invention is directed to a sensing device for monitoring conditions at a remote location and a method therefor. Particularly, the instant invention is for a sensing
5 device that monitors the conditions of a container at a remote location and a method therefor. More particularly, the disclosed invention is for a sensing device that monitors the level of waste materials in a waste disposal container at a remote location and, then, relays this information to allow for the
10 emptying of the waste disposal container.

BACKGROUND OF THE INVENTION

[0004] The amount of trash is an ever-growing problem. This is especially true in the retail and commercial sectors, where
15 a large amount of refuse is discarded daily. Most businesses have trash bins adjacent to their buildings for dumping the totality of trash collected either daily or throughout the day. The rate at which the garbage piles up in these trash receptacles varies according to factors such as the season, the industry, the
20 location, etc. Consequently, different businesses and different locations of a business may require different pick-up times for their trash bins.

[0005] To minimize the cost of hiring commercial trash collection services to pick-up the trash from the trash
25 receptacles, some companies may designate standard pick-up times,

such as daily or weekly, even though the trash bins may not be full. Other companies may call commercial trash collection services only when their trash bins are full. Either way, the company usually must use the telephone to call the commercial
5 trash collection service.

[0006] The detection of the level of trash in trash receptacles is known in the art. Such detection usually entails some device or method used within the receptacle that senses the level of trash. For instance, a photoelectric cell has been
10 employed for this purpose, as described in U.S. Pat. No. 3,765,147 to Ippolito. Another variation measures the pressure exerted on the trash compactor to detect when the receptacle is full, as disclosed in U.S. Pat. No. 4,773,027 to Neumann. Still, U.S. Pat. No. 3,636,863 to Woyden teaches using pressure-sensing
15 means to determine when the trash container is full.

[0007] Additionally, it is known in the art to utilize a means for relaying the information regarding the fullness of the trash receptacle to another location, where the information can be processed. Usually, this relaying method encompasses a telephone
20 or cellular phone line. Some of these devices include U.S. Pat. No. 5,558,013 to Blackstone, Jr.; U.S. Pat. Nos. 5,299,493 and 5,303,642 to Durbin et al.; U.S. Pat. No. 5,214,594 to Tyler et al.; and U.S. Pat. Nos. 5,173,866 and 5,016,197 to Neumann et al.

25 [0008] While each of these systems are useful, they are

burdened by several significant disadvantages:

First, they fail to minimize the expenses of telephone toll charges when transmitting information regarding the trash receptacles via a telephone line. This charge may be quite expensive, in light of the fact that some systems maintain a multitude of trash containers.

Second, they do not allow users to measure the amount of power supply left in the transmitting means. If the power supply runs out, the waste disposal detection system would be rendered useless.

Third, the references do not disclose a way to conserve energy and, thus, allow one to save on more expenses. And, since these references fail to conserve energy, they are not optimally environmentally friendly.

Fourth, the references do not disclose a means to verify that the measurements of the waste disposal container are valid, thereby preventing false readings which may also result in unnecessary charges in emptying a container that is not completely full.

BRIEF SUMMARY OF THE INVENTION

[0009] The instant invention is for a sensing device that may be used for detecting various conditions at remote locations.

In particular, one embodiment of the invention is directed to a sensing device for detecting the conditions of a container at a

remote location. Another embodiment would be used to detect conditions in a waste disposal container at a remote location.

[0010] Generally, this invention features three main components: a transmitting module, a receiving module and an identifying means. While each transmitting module is paired with one base module, each base module may be matched with a multitude of transmitting modules at any one remote location to accommodate the number of containers at that location. Moreover, there may be numerous remote locations comprising such pairings.

10 [0011] The invention also comprises a detecting means for detecting the conditions at the remote location. The detected information is sent to the transmitting module, which has a reading means and a transmitting means. The reading means reads the detected information. In practical usage, the transmitting
15 module also has a first power source for supplying power thereto. The first power source has a power level that is also read by the reading means. The transmitting means sends the information pertaining to the conditions of the remote location and the power level of the first power source to the base module, which is
20 located near the transmitting module. Advantageously, the transmitting module is only turned-on for approximately 10 seconds, during which time it completes all of its functions. This results in substantial savings in energy charges and is environmentally-friendly.

25 [0012] The base module comprises a receiving means, a first

processing means and a conveying means. The receiving means receives the transmitted information from the transmitting module and, then, sends the information to the first processing means of the base module. In one embodiment of the present invention, 5 information from containers located at a close proximity to the base module may be sent directly to the first processing means, without utilizing a transmitting module. Additionally, the base module may have a second power source whereby the power level of this power source is also sent to the first processing means. 10 The first processing means selectively processes all of the information it receives to determine which of a list of pre-programmed telephone numbers to call. In other words, each telephone number matches-up with each of the conditions of the remote location, the amount of power supply in the first and 15 second power sources, and the conditions of the containers located at a close proximity to the base module. The conveying means relays the transmitted information by calling the selected telephone number.

[0013] An identifying means is used to identify the remote 20 location of the call. This is typically accomplished by identifying the originating telephone number of the remote location. In the most preferred embodiment, the identifying means identifies the data being transmitted in as little time as possible. This is accomplished through the use of a second 25 microprocessor having a CALLER ID unit that can identify the

location of the originating call without having to "answer" or "connect" the call. Once the originating telephone number of the remote location is identified, one embodiment of the invention would allow for the container or trash receptacle at the remote
5 location to be emptied or for the power level of the first power source to be recharged.

[0014] Another embodiment of the present invention is a method of monitoring the conditions at a remote location. Two other embodiments of the invention include: (1) a method for remotely
10 monitoring the conditions of a container; and (2) a method for remotely monitoring the conditions of a trash receptacle.

[0015] It is, therefore, an object of the present invention to teach a means for alleviating the problems associated with the prior art systems of trash receptacle detection.

15 [0016] It is an object of the instant invention to provide a sensing device for monitoring conditions at a remote location and a method therefor.

[0017] It is also an object of this invention to provide a sensing device for monitoring the conditions of a container at
20 a remote location and a method therefor.

[0018] It is another object of the present invention to provide a sensing device for monitoring the conditions of a waste disposal container and a method therefor.

[0019] A further object of this invention is to provide a
25 sensing device that transmits its data in as little time as

possible, and a method therefor.

[0020] It is also an object of the instant invention to provide a sensing device that measures the power supply of the transmitting means and a method therefor.

5 [0021] Another object of the present invention is to provide a sensing device that conserves the consumption of energy used by the device and a method therefor.

[0022] It is a further object of this invention to provide a sensing device that is environmentally friendly and a method
10 therefor.

[0023] It is an object of the present invention to provide a means to verify the information regarding the conditions of a container.

[0024] There has thus been outlined, rather broadly, the more
15 important features of the invention in order that the detailed description thereof that follows may be better understood, and in order that the present contribution to the art may be better appreciated. There are, of course, additional features of the invention that will be described hereinafter and that will form
20 the subject matter of the invention. Those skilled in the art will appreciate that the conception, upon which this disclosure is based, may readily be utilized as a basis for the designing of other devices for carrying out the several purposes of the present invention. It is important, therefore, that the
25 invention be regarded as including such equivalent constructions

insofar as they do not depart from the spirit and scope of the present disclosure.

BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWINGS

5 [0025] The foregoing and other additional objects of the present invention will be readily appreciated by those skilled in the art upon gaining an understanding of the invention as described in the following detailed description and shown in the accompanying drawings in which:

10 [0026] FIG. 1 is a block diagram illustrating the generalized embodiment of the sensing device of the present invention.

[0027] FIG. 2 is a flow diagram showing the steps of the general embodiment of the method of monitoring conditions at a remote location of the present invention.

15 [0028] FIG. 3 is a schematic block diagram displaying another embodiment of the sensing device of the present invention in which the conditions of a container are monitored by the sensing device.

[0029] FIG. 3A shows details of the transmitting module.

20 [0030] FIG. 3B shows details of the base module.

[0031] FIG. 4 is a block diagram illustrating one embodiment of the conserving means used in the transmitting module.

[0032] FIG. 5 is a flow diagram showing the process of conserving the power level of the first power source in the
25 transmitting module.

[0033] FIG. 6A is a flow diagram of one embodiment of the method of monitoring conditions of a waste disposal container at a remote location and matching the conditions to a telephone number.

5 [0034] FIG. 6B is a flow diagram of one embodiment of the method of monitoring conditions of a waste disposal container located at a close proximity to the base module and matching the conditions to a telephone number.

[0035] FIG. 6C is a flow diagram of one embodiment of the
10 method of calling the telephone number matched in FIGS. 6A & 6B and conveying information regarding the monitored conditions.

[0036] FIG. 7 is a block diagram illustrating one embodiment of the off-hook detecting means used in the base module.

15 DETAILED DESCRIPTION OF THE INVENTION

[0037] Referring to the drawings, FIG. 1 shows a block diagram of four sensing devices **10** of the instant invention. Each sensing device **10** comprises, generally, detecting means **14**, a transmitting module **18**, a base module **22** and identifying means
20 **26**. The detecting means **14** and the transmitting module **18** are located at a remote location **12** (shown as dotted rectangular areas in FIG. 1). The detecting means **14** detects conditions at the remote locations **12**. Lines **16** show that the detected information is sent to a transmitting module **18**. The

transmitting module **18** reads the information before transmitting the information, shown by dotted-line **20**, to a base module **22**.

[0038] When the base module **22** receives the transmitted information, it processes the information to determine which
5 number from a database **136** of pre-programmed telephone numbers to call (shown as step **38** in FIG. 2). This call is shown by line **24**, which also shows the information being conveyed to the identifying means **26**. As FIG. 1 depicts the general embodiment of this invention, other embodiments will be apparent in the
10 following descriptions of the relevant figures. For instance, since the identifying means **26** necessarily identifies the remote location **12** of the call by identifying a telephone number, it follows that each remote location **12** must have its own originating telephone number. Also, even though only one
15 identifying means **26** is shown in FIG. 1, it will be shown *infra* that there most likely comprises a multitude of identifying means **26** to match-up with the host of different conditions processed by the base module **22**.

[0039] FIG. 2 is a flow diagram depicting the generalized
20 method for monitoring conditions at a remote location **12**. Step **28** detects the conditions at the remote location **12**. Step **30** reads the detected conditions. Next, the information regarding the detected conditions are transmitted by step **32** and received by step **34**. The information is processed by step **36** to determine

which pre-programmed telephone number to call. Step 38 calls the selected pre-programmed telephone number, while step 40 conveys the transmitted information. The remote location 12 of the call is, then, identified by step 42. In this embodiment, 5 steps 30 and 32 occur in the transmitting module 18; steps 34 to 40 occur in the base module 22; and step 42 occurs in the identifying means 26.

[0040] Another embodiment of this invention is shown in FIG. 3, in which a sensing device 10 monitors the conditions of a 10 container 44 at a remote location 12. The container 44 may be any type of container that holds materials, such as liquids or solids. The conditions of the container 44 include whether the container 44 is full or empty, the level of the contents 45 in the container 44, or any other condition that the user needs to 15 monitor. A detecting means 14 is used to analyze the conditions of the container 44. Detecting means 14 that are compatible with the instant invention include conventional detecting means 14 disclosed in U.S. Pat. Nos. 3,765,147, 4,773,027, and 3,636,863 (cited above). Preferred detecting means 14 include switch 20 inputs 88 and ultrasonic ranging units 130. The most preferred ultrasonic ranging units 130 comprise units made by Polaroid.

[0041] But, the most preferred detecting means 14 are switch inputs 88. The switch inputs 88 of this embodiment are connected by wires 47, also called hard wire inputs, to the container 44.

The contents **45** inside of the container **44** are typically oil and grease. A float is placed on top of the contents **45** whereby the float is connected to a first end of the wires **47**. The second end of the wires **47** is connected to the switch inputs **88**, which 5 are themselves secured in the transmitting modules **18**. In operation, the float will rise and fall depending on the level of the contents **45** in the container **44**, and this information will be sent to the switch inputs **88**. Each switch input **88** matches with a condition of the container **44**. The preferred embodiment 10 would utilize three switch inputs **88** to indicate whether the container **44** is 3/4 full (input 3 **88c**), 1/2 full (input 2 **88b**) or 1/4 full (input 1 **88a**). If the container **44** is empty, none of the switch inputs **88a-88c** will be activated.

Sub C1

[0042] A further embodiment of the present invention 15 illustrated in FIG. 3 and FIG. 3A is a first power source **50**, such as a battery that provides power to the transmitting module **18**. The first power source **50** has a power level that can be measured by a measuring means to determine when it is low and, thus, needs to be recharged or changed. A first power source **50** 20 that may be used with this invention is a battery supply **50**, most preferably a 9-volt battery.

[0043] The information regarding the conditions of the container **44** is sent by the detecting means **14** to the reading means **46** of the transmitting module **18**. The reading means **46**

reads both the information from the detecting means **14** and the power level 2 of the first power source **50**, and transfers the information to the transmitting means **54**. The preferred reading means **46** comprises a combination of at least one transistor **56**,
5 at least one resistor **58** and an encoder **60** per switch **88**, when a preferred switch input **88** is used. The transistor **56** conveys high and low switch information to the encoder **60**, and the resistor **58**, along with a capacitor **61**, limits the current to protect the transistor **56** from damage and noise/static. It is
10 preferred that the transistor **56** comprises a 2N3904 transistor **56**. The resistors **58** comprise 10 kilo-ohm resistors **58a**, while the capacitor **61** comprises a 0.1 microferad-50 volt ceramic capacitors **61**. In another embodiment of the instant invention, a measuring means **62** is used to measure the power level of the
15 first power source **50**. Thereafter, the measuring means **62** also conveys the power level information to the encoder **60**. It is further preferred that the encoder **60** comprise an encoding integrated circuit (IC). The most preferred encoder **60** is a Holtek Encoder HT-12E that is commercially available. The
20 measuring means **62** is preferably one half of an operational amplifier (OpAmp) circuit **64**, a plurality of resistors **59** and a voltage reference **65**. The most preferred OpAmp circuit **64** comprises a model LM2903 OpAmp circuit. The preferred resistors **59** used in the measuring means **62** comprise a 10 kilo-ohm resistor

59a, a 100 kilo-ohm resistor 59c and a 7.5 kilo-ohm resistor 59b. The most preferred voltage reference 65 comprises a 2.5 volt voltage reference having model number LM285-2.5.

Sub C2 [0044]

Still referring to the same embodiment in FIG. 3 and 5 FIG. 3A, a delaying means 66 may be used to delay the encoder 60 from transmitting the data until all the circuitry of the encoder 60 is powered up and stable. The delaying means 66 is preferably the other half of the OpAmp circuit 64 described above used in conjunction with a plurality of resistors 69 and a 10 capacitor 61. The most preferred OpAmp circuit 64 comprises the model LM 2903 OpAmp circuit identified above. The plurality of resistors 69 most preferably comprises two 10 kilo-ohm resistors 69a and one 100 kilo-ohm resistor 69c. It is also preferred that the capacitor comprises a 0.1 microfarad capacitor 63.

15 [0045] Another embodiment of the transmitting module 18 depicted in FIG. 3 is a conserving means that is used to conserve the power level of the first power source 50. Preferably, the conserving means comprises an activating means 70 that only activates the first power source 50 of the transmitting module 20 18 at periodic intervals. The most preferred activating means 70 comprises a slow timing circuit 72 that is shown in more detail in FIGS. 4 and 5 and is discussed *infra*.

Sub C3 [0046]

Still referring to FIG. 3 and FIG. 3A, the transmitting means 54 preferably comprises an encoder 60, which is most

preferably the same encoder **60** used for the reading means **46**. The encoder **60** transmits data over an RF link **256**, shown by line **20**, to the base module **22**. This is accomplished by using an AM transmitting unit **74** or an FM transmitting unit **76**. Preferably, 5 the AM and FM transmitting units **74** and **76** may comprise the AM-RT4-433 unit **74** or the TXM-433-A unit **76**, respectively, both manufactured by Abacom Technologies. Each bit of information transmitted by the transmitting means **54** represents one condition. For instance, information pertaining to the three 10 different levels of the container **44**-- that is, 3/4 full, 1/2 full and 1/4 full-- and the power level of the first power source **50** comprise four conditions which represents 4-bits of information.

[0047] Next, referring to FIG. 3 and FIG. 3B, the receiving 15 means **78** of the base module **22** receives the transmission from the transmitting means **54**. In particular, the receiving means **78** comprises a receiver **80** and a decoder **82**. In operation, the receiver **80** receives the data sent from the transmitting means **54** and conveys the data to the decoder **82**. The receiving means 20 **78** is preferably an RF receiving unit so that it can receive transmissions over the RF link **256**, shown by line **20**. The preferred receiver **80** comprises either an AM receiver **80a** or an FM receiver **80b**, most preferably either the AM-HRR3-433 receiver or the SILRX-433-A receiver, respectively, both manufactured by

Abacom Technologies. The decoder **82** is preferably a Holtek decoder **82**, most preferably the HT-12D unit.

[0048] Dip switches may be used in both the transmitting module **18** and the base module **22** to change the addresses, 5 respectively, of the encoder **60** and the decoder **82**. This allows for multiple pairings of transmitting modules **18** and base modules **22** at the same remote location **12**, shown in FIG. 1, which results in the detection of a number of containers **44** at the same location **12**. The binary address of a transmitting module **18** is 10 matched with the binary address of a base module **22** so that the two modules **18** and **22** may communicate with each other. The most preferred dip switches are four-position dip switches **178** because they allow for sixteen different addresses to exist at a single location **12**. Preferred four-position dip switches **178** are C&K- 15 BD04 dip switches. It is further preferred that the transmitting module **18** and the base module **22** not be farther than 300 feet apart.

[0049] The decoder **82**, then, conveys the received data to the first processing means. Preferably, the first processing means 20 comprises a first microprocessor **86**. The most preferred first microprocessor **86** is the Atmel AT89S8252 microprocessor **86**. A rapid timing circuit **346** is used in conjunction with the first microprocessor **86** to constantly activate the first microprocessor **86**. The rapid timing circuit **346** preferably comprises a rapid

oscillator **206a** and two capacitors **84**. The preferred rapid oscillator **206a** comprises a crystal oscillator, most preferably an 11.0592 mega-hertz xtal oscillator. The preferred capacitors **84** comprise 33 picofarad ceramic capacitors.

5 [0050] It is further preferred that the base module **22** has six switch inputs **88** (discussed *infra*) and transferring means **90**, whereby the six switch inputs **88a-88f** convey high/opened and low/closed switch information to the transferring means **90** which, then, conveys that information to the first microprocessor **86**.

10 As discussed *supra*, three **88a-88c** of the six inputs **88a-88f** may match-up with the level of the contents in a container, while the other three inputs **88d-88f** may match up with other conditions, such as the level of contents in other containers. If a switch input **88** is in the high/opened state, then the first

15 microprocessor **86** will not match the condition with a telephone number. But, if a switch input **88** is in the low/closed state, then this is considered an "active" state and the first microprocessor **86** matches the appropriate telephone number with the condition to prepare for that number to be dialed (shown in

20 FIG. 6B). The transferring means **90** protects or buffers the external surroundings from the inputs **88** to the first microprocessor **86** to prevent interference therefrom. The preferred transferring means **90** is an inverter, the most preferred inverter being a trigger inverter. The most preferred

trigger inverter is a Schmidt trigger inverter IC **U6** having model number 74HC14.

[0051] The base module **22** is powered by a second power source **98**. The second power source **98** is preferably a transformer, most preferably a wall transformer **102** having a 12 volt DC output, such as the 12 volt-500ma DC - CUI STACK#DPD120050-P-5 wall transformer. The wall transformer **102** feeds power, sequentially, to a power input jack **104**, a full wave bridge circuit **106** and a regulator **108**. The regulator **108**, then, feeds power to the rest of the internal circuitry of the base module **22**. The full wave bridge circuit **106** allows any polarity of DC input to power the base module **22** and is, most preferably, a full wave bridge circuit **106** made up of four 1N4004 diodes **107**. The regulator **108** is most preferably a 5-volt regulator **108**, such as the 7805-voltage regulator unit, that converts the incoming 12 volts DC from the wall transformer **100** to a lower power level of 5 volts.

[0052] As a precaution against losing the operating program (disclosed in the MICROFICHE APPENDIX attached hereto and discussed *infra*) that is running the first microprocessor **86**, there is a watchdog IC **114** that generates a reset pulse to restart and power-up the first microprocessor **86**. To prevent the watchdog IC **114** from generating the reset pulse, it is preferable to utilize a strobe input in the watchdog IC **114** that is periodically strobed or toggled by the first microprocessor **86**.

While the strobe input is toggled, the watchdog IC **114** will not generate a reset pulse. But, if the first microprocessor **86** stops toggling the strobe input, the watchdog IC **114** will, after a set time period, generate a reset pulse to restart the first 5 microprocessor **86**. The most preferred watchdog IC **114** is the Maxim MAXCPA1232uP supervisor unit.

SubC4 [0053] Continuing with FIG. 3 and FIG. 3B, the base module **22** preferably has at least one external first-indicator **120** and means for turning on the first-indicator **120**. The first-10 indicator **120** allows human operators to supervise the conditions of the base module **22** by connecting the first indicator **120** to the first processing means of the base module **22**. The means for turning on the first indicator **120** most preferably comprises at least one transistor **124**, while the first-indicator **120** comprises 15 at least one lamp. The most preferred lamp is at least one light emitting diode (LED) **174**. In the most preferred embodiment, the first processing means relays data to the transistors **124** which lights the light emitting diodes **174**, thus alerting operators on the scene of any problems. The preferred transistors **124** 20 comprise MPS-A18 transistors. The first-indicator **120** can be used to alert operators regarding the different conditions of the remote location **12**, the transmitting module **18** or the base module **22**, depending on the preference of the user. The most preferred conditions indicated comprise: the low power level of the second

power source **98** of base module **22**; the different levels of the containers **44**; telephone dialing in progress; the low power level of the first power source **50** of the transmitting module **18**; and that valid data has been received from the transmitting module
5 **18**.

[0054] At least one second indicator **194** shown in FIG. 3B may be used to supplement the first-indicator **120**. The second indicator **194** is most preferably also an LED. The specific process encompassing this embodiment is discussed *infra* and
10 illustrated in FIG. 6B. In the preferred embodiment, the first indicator **120** is a light source that can be seen from a distance to alert operators of potential problems, while the second indicator **194** is an LED **175** on the base unit **22** that can be viewed at a close range thereto. Additionally, multiple first
15 indicators **120** and second indicators **194** may be utilized to indicate different conditions, a sample of which is illustrated in FIG. 6B and its corresponding discussion *infra*. The most preferred LEDs **175** used for the second indicators **194** comprise size T-1 LEDs **175**. Resistors **58b** may be used in series with the
20 LEDs **175** to limit the current running through the LEDs **175**. Preferred resistors comprise 470-ohm resistors **58b**.

[0055] The base module may also have reporting means **128** that report conditions at a close proximity to the base module **22**. FIG. 3 and FIG.3B illustrates the reporting means **128** reporting

the conditions of a container **44** located near the base module **22**. The reporting means **128** operates in the same manner as the detecting means **14** described above. As such, the reporting means **128** may comprise any of the types of devices discussed for the 5 detecting means **14**. But, the most preferred reporting means **128** are switch inputs **88** shown in FIG. 3B. However, alternatively, ultrasonic ranging units **130** shown schematically in FIG 3 can be used. Either way, the reporting means **128** utilizes wiring **47** to send data from the container **44** to the first processing means **84** 10 of the base module **22**. The preferred wiring **47** is hard wire inputs. If an ultrasonic ranging unit **130** is used as the reporting means **128**, it would use the first microprocessor's **86** internal timing functions to measure the time it takes for an ultrasonic pulse to travel from the top of a container **44** to the 15 contents **45** therein and, then, back to the top to compute the level of the contents **45** in the container **44**. The most preferred ultrasonic ranging units **130** comprise units made by Polaroid. However, if the switch inputs **88** are used, they would be used in the same manner as described above for the detecting means that 20 is, with a float placed on top of the contents **45** within the container **44**. Most preferably, each of the switch inputs **88a-88f** are connected to connectors to facilitate external connections to the reporting means **128**. The preferred connectors comprise dual row 12-pin right angle "Molex Microfit" connectors.

[0056] The conveying means **134** of the base module **22** conveys the data processed by the first processing means **84** to the identifying means **26**, as shown by dotted line **24**. It accomplishes this by calling the telephone number determined by
5 the first processing means **84** which matches each condition with an appropriate telephone number, as selected from a list of pre-programmed telephone numbers, identified in FIG. 3 as a pre-programmed telephone number database **136**. The database **136** is ideally stored in non-volatile memory **138** inside the first
10 microprocessor **86**. The selection of the appropriate telephone number by the first processing means **84** is accomplished by the novel software program attached to this patent application, as disclosed in the MICROFICHE APPENDIX. The MICROFICHE APPENDIX and FIGS. 6A-6B also disclose the process by which the
15 appropriate telephone number is selected.

[0057] Still referring to the conveying means **134**, it preferably comprises a microprocessor, most preferably the first microprocessor **86** used for the first processing means **84**. The microprocessor is connected to a modem **142** and an operating
20 program. Modems **142** are commercially available, but the preferred modem **142** is a Cermetec modem having part number 1786LC.

[0058] Another component of the conveying means **134** is telephone lines **146** (shown in FIG. 7) used to convey the data.

When telephone lines **146** are used, one of skill in the art will know to use telephone jacks **148** (shown in FIG. 7) in the base module **22** for connecting the telephone lines **146** to the base module **22**. The most preferred telephone jacks **148** comprise 5 Corcom RJ11-2L-S telephone jacks **148**. It is to be understood that cellular telephones may be used as a substitute component for telephone lines **146**, in which case modems **142** adapted for use with cellular telephones are required, along with other devices known in the art for utilizing cellular telephones. Thus, line 10 **24** depicts data transmissions by either telephone lines **146** or cellular telephones. FIG. 7 illustrates an off-hook detecting means **348** that detects whether the telephone line **146** is in use (off-hook) or not in use (on-hook) and is described in detail *infra*.

15 **[0059]** Updating means may be used to update the information stored in both the pre-programmed telephone number database **136** and the operating program of the microprocessor. The most preferred updating means is a connector. The preferred connector comprises the 9-pin female D-subminiature right-angle board mount 20 "Amp 745781-4" connector.

[0060] Often, electrical noise on telephone lines **146** can damage the circuitry as it travels between the modem **142** and the telephone lines **146**. Protecting means are preferably used to protect the circuitry. Preferable protecting means include

additional circuitry in the form of high voltage capacitors **162**, ferrite beads **164**, resettable fuses **166** and surge protectors **168**. The most preferred ferrite beads **164** comprise the "Fair-Rite" 264366611 ferrite bead **164a** or the "Fair-Rite" 2943666661 **164b** ferrite bead. The most preferred resettable fuses **166** comprise Raychem Polyswitch TR600-150 fuses, while the most preferred surge protectors **168** comprise Teccor Sidactor P3203AB surge protectors. When cellular telephones are used as the conveying means **134**, electrical noise is not a problem, such that protecting means are not required.

[0061] Referring to FIG. 3, the identifying means **26** receives the data sent by the conveying means **134** of the base module **22**. Specifically, a second processing means **180** having a CALLER ID unit **182** is the preferred identifying means **26**. If the second processing means **180** is not used, a CALLER ID unit **182** may be used by itself as the identifying means **26**. Either way, the CALLER ID unit **182** is the component that initially receives the data sent by the conveying means **134**. Preferable CALLER ID units **182** comprise the "WhozzCalling?Lite4"(TM) and "Whozz Calling?Lite8"(TM) units made by Zeus Phonstuff, Inc., Norcross, Georgia, that is commercially available. Furthermore, a printer **184** may be connected to the second processing means **180** so that the data identified by the identifying means **26** may be printed as a written record. The most preferred second processing means

180 is a second microprocessor. It is also preferred that the second microprocessor utilizes a hard drive or a floppy drive (not shown), or most preferably both, to store data comprising information regarding the location **12** of the incoming call.

5 **[0062]** Once the identifying means **26** identifies the remote location **12** of the originating call to the pre-programmed telephone number, and before the receiving means answers the call, a disconnecting means **186** may be used to disconnect the call, whereby the information is passed before a call is
10 completed. This results in substantial savings for the user. The disconnecting means **186** is most preferably located in the base module **22** and connected to the conveying means **132**. The typical disconnecting means **186** comprises a modem **142**, preferably the same modem **142** used to call the identifying means **26**
15 described above. Further, the disconnecting means **186** optimally allows the telephone call to ring for a time period equivalent to four rings before disconnecting the call, so that the identifying means **180** may identify the remote location **12** of the call. The number of telephone rings may vary depending on one's
20 preference.

[0063] Since the conveying means **132** calls different pre-programmed telephone numbers for different conditions, one can determine from observing the identifying means **26** which condition corresponds with which remote location **12**. As a result, one can

send, shown by line 200, either emptying means 196 or recharging/changing means 198, or both, to the appropriate remote location 12 or to a location at a close proximity to the base module 22 to remedy the problem. It is most preferable that the 5 second processing means 180 comprise software to make the decision shown by line 200. This software could also be programmed to print out a report detailing the conditions from the transmitting module 18 and/or the base module 22. Software that is compatible with the second processing means 180 comprises 10 the "Callwhere(R) Plus for Windows" program made by A&A TeleData, Austin, Texas, that is commercially available.

[0064] Emptying means 196 may involve using a human operator (not shown) to physically empty the container 44 or it may involve contacting a commercial service (not shown) to empty the 15 container 44. Recharging means 198 include either recharging or changing the first 50 or second 98 power source.

[0065] Referring now to FIG. 4, the conserving means 68 of the transmitting module 18 is shown in a block diagram. The specific embodiment displayed is a slow timing circuit 72 (indicated by 20 a dotted rectangular area) that only activates the transmitting module 18 at periodic intervals. The slow timing circuit 72 comprises a counter 204 having an oscillator 206 and an RC time constant 208. The oscillator 206 preferably comprises a slow oscillator. The RC time constant controls the frequency of the

slow oscillator 206, as shown by line 212. The counter 204 triggers a one-shot circuit 214 within the slow timing circuit 72 when a pre-selected count is reached, shown by line 218. The one-shot circuit 214 is only activated for 10 seconds so as to conserve energy. Thereafter, the one-shot circuit 214 turns on the first power source 50 of the transmitting module 18, depicted by line 220. The activated one-shot circuit 214 also resets the counter 204 back to its starting count, illustrated by line 222. The most preferred counter 204 is a CD4060BCN counter, while the most preferred one-shot circuit 214 is a CD4538BCN one-shot circuit.

[0066] FIG. 5 shows a flow diagram of the process of conserving the power level of the first power source 50. A starting count 224 is initially set at zero. Then, step 226 shows that the counter 204 starts the count. Step 228 decides whether the pre-selected count has been reached. The most preferred pre-selected count set to five hours, but one of skill in the art will know that the pre-selected count is variable depending on one's preferences and needs. If the pre-selected count has not been reached, then the count continues, as shown by line 229a. But, if the pre-selected count is reached, line 229b shows that the next step 230 is to trigger the one-shot circuit 214 for 10 seconds. Once the one-shot circuit 214 is triggered, step 232 activates the first power source 50 of the

transmitting module **18** and step **234** resets the counter **204** back to the starting count to start the process again, all within the 10 seconds of activation. In the manner described above, the power level of the first power source **50** is not continually used; rather, the first power source **50** is only activated at periodic intervals for merely 10 seconds to run the transmitting module **18**. The transmitting module **18** uses the most power when it is transmitting data during this short time period. Otherwise, the conserving means causes the transmitting module **18** to "sleep" and not consume the power of the first power source **50**. This results in large monetary savings for the user and is also environmentally friendly.

[0067] FIG. 6 is split into three flow diagrams which, in totality, illustrate one preferred embodiment of the instant invention in which: FIG. 6A illustrates the process of monitoring the conditions of a waste disposal container at a remote location **12**; FIG. 6B shows the process of monitoring the conditions of a waste disposal container at a close proximity to the base module **22**; and FIG. 6C illustrates the process of conveying the conditions monitored by FIGS. 6A and 6B so that appropriate steps are taken to remedy the conditions. Both FIG. 6A and FIG. 6B emphasize the steps of matching the monitored conditions with one of the telephone numbers selected from the list of pre-programmed telephone numbers in database **136**.

[0068] Referring firstly to FIG. 6A, step **238** detects the conditions of the waste disposal container at the remote location **12**. Step **240** measures the power level of the first power source **50**. Step **241** activates the transmitting module **18** using the 5 conserving means. Step **242** reads the information obtained during steps **238** and **240**. Next, the information is encoded by step **244**. Transmission of the information is delayed by step **246** until all circuitry is powered up and stable. Step **248** decides whether all of the circuitry is powered up and stable. If not, line **250** 10 shows that the transmission must be delayed by step **246** until the answer to step **248** is in the affirmative. But, if the answer to step **248** is yes, then line **252** indicates that the information is transmitted by step **254**, which shows the process of transmitting the information over the preferred RF link **256**. After the 15 information is transmitted by step **254**, dotted-line **257a** shows that the transmitting module **18** goes to sleep as step **257**. Dotted-line **257b** illustrates that the transmitting module **18** sleeps until it is activated again by step **241**.

[0069] The transmitted information is received by step **258** and 20 decoded by step **260**. Step **262** shows that the information must be firstly verified, because an initial transmission by the transmitting step **254** may contain a false reading of the level of the contents **45** in the waste disposal container. To prevent the processing of false readings, a second transmission received

by the receiving step **258** must contain the same information as the initial transmission for the information to be considered valid. The initial and second transmission-- called consecutive transmissions-- must necessarily occur at five-hour intervals in
5 the preferred embodiment, because the transmitting module **18** is only activated by the activating step **241** every five hours. For example, if, during the initial transmission, the contents **45** in the waste disposal container **236** did not settle, any readings of such information would be inaccurate. Thus, during the second
10 transmission, if the contents **45** have settled, then a different reading would be taken, and the information received from consecutive transmissions of step **254** would not be the same and, hence, would not be firstly verified by step **262**. Consequently, only two consecutive transmissions having the same readings would
15 comprise valid information.

[0070] Additionally, to further ensure that the information transmitted by step **254** is valid, receiving step **258** disables the base unit **22** for twenty seconds after it receives information from the transmitting module **18**. As a result, no information,
20 whether containing false readings or not, may be received by step **258** during this twenty-second period.

[0071] Continuing with FIG. 6A, step **264** decides whether the transmitting step **254** sent two consecutive transmissions. If not, then line **266** shows that the receiving step **258** is revisited

to determine whether more transmissions are forthcoming from step
254. If the transmitting step 254 does send two consecutive
transmissions, at five-hour intervals, then line 268 leads to a
series of steps which match a condition at the remote location
5 12 with a telephone number from the list of pre-programmed
telephone numbers in database 136.

[0072] Step 270 decides whether the remote waste disposal
container is 3/4 full or more. If so, then line 271a leads to
step 300 which matches ("matching step") that condition with a
10 telephone number. It is important to note that the matching
steps 300 disclosed in FIGS. 6A-6C are all typically conducted
by the novel software program disclosed in the MICROFICHE
APPENDIX attached hereto. If the answer to step 270 is in the
negative, line 271b leads to step 272 to determine whether the
15 remote waste disposal container is 1/2 full or more. If so, then
line 273a leads to the matching step 300 to match that condition
with a telephone number. If the answer to step 272 is in the
negative, then line 273b leads to step 274 to decide whether the
remote container is 1/4 full or more. If so, then line 275a
20 leads to the matching step 300. If not, then line 275b leads to
step 276.

[0073] Step 276 determines whether the remote trash container
just made a transition from being either 1/2 or 3/4 full, or
more, to being empty. If so, line 277a leads to the matching

step **300**. If not, line **277b** leads to step **278**, which determines whether the power level of the first power source **50** is low. If the power level is low, line **279a** leads to the matching step **300**. But if the power level is not low, line **279b** leads to step **280**
5 to determine whether the transmitting module **18** is responding properly. If the transmitting module **18** is not responding properly, line **281a** leads to the matching step **300**. However, if the transmitting module **18** is responding properly, then line **281b** indicates that receiving step **258** is revisited to prepare to
10 receive another transmission from the transmitting module **18**. Incidentally, the order of steps **270-280** is not of paramount importance. One skilled in the art will know that these steps may be arranged in any order to suit one's preference.

[0074] Monitoring the transition of the remote trash container
15 from being 1/2 or 3/4 full, or more, to being empty via step **276** is important because experience shows that some remote trash containers **44**, may have their contents **45** stolen. It is favorable, then, for the activating step **241** to be "awakened" immediately in such circumstances so that this information may
20 be transmitted by step **254**. The quicker activation of step **241** may be adjusted depending on the user's preference. Thus, once this transition is detected and received by step **258**, then step **300** matches the appropriate telephone number with this condition, thereby allowing the steps illustrated in FIG. 6C (discussed

below) to convey this transition. The desired result is to catch potential thieves in the act, or shortly thereafter.

[0075] Referring now to FIG. 6B, step **282** reports the conditions of any waste disposal containers in close proximity to the base module **22**, and step **284** reports the power level of the second power source **98**. Step **286** decides whether the power level of the second power source **98** is low. If the second power source **98** is at low power, line **287a** will lead to step **300** to match this condition with a telephone number from the list of pre-programmed telephone numbers in database 136. Step **300** is the same as the match step **300** disclosed in FIG. 6A, so it will also be termed the "matching step" **300**. If, however, the power level of the second power source **98** is not low, then line **287b** will lead to step **284** to continue reporting the power level. Steps **284-286** are preferably utilized when the second power source **98** is a battery, since batteries tend to be used up sooner than the power from a transformer **100** (disclosed above).

[0076] The information reported by step **282** must be secondly verified by step **288**. Step **288** is similar to step **262** (shown in FIG. 6A and its accompanying discussion) in that the former ensures that no false readings are reported by step **282**. However, since step **282** is not subject to the five-hour interval transmissions of step **254** (shown in FIG. 6A), another verifying technique must be utilized. As such, the secondly verifying step

288 is accomplished by the preferred switch inputs 88 staying in the same high/opened or low/closed state for three seconds to allow the contents 45 of the waste disposal container to stabilize or to allow for any electrical noise to be ignored before the information is considered valid. Step 290 determines whether the information reported by step 282 is constant for three seconds. If not, line 291a returns to step 288 to attempt to verify the reported information. If so, line 291b shows that the reported information is considered valid.

10 [0077] Still referring to FIG. 6B, step 292 determines whether the waste disposal container located at a close proximity to the base module 22 is 3/4 full or more. If so, line 293a leads to step 294 to light a green 174a, yellow 174b and red 174c light emitting diode ("LED"). The LEDs 174a-174c disclosed in FIG. 6B provide operators stationed at or near the base module 22 with notice of the level of the trash container located near the base module 22. Line 295 indicates that once the LEDs 174a-174c are lit, the condition is matched with a telephone number by the matching step 300. If the answer to step 292 is in the negative, 15 line 293b leads to step 296 to determine whether the waste disposal container is 1/2 full or more. If so, line 297a leads to step 298 to light the green 174a and yellow 174b LED. Then, line 299 leads to the matching step 300. But if the container is not 1/2 full or more, line 297b leads to step 302 to decide

whether the trash container is 1/4 full or more. If so, line 303a leads to step 304 to light the green LED 174a. Thereafter, line 305 leads to the matching step 300. If the answer to step 302 is in the negative, then line 303b leads to step 306 to
5 determine whether the waste disposal container has undergone the transition from 1/2 or 3/4 full, or more, to empty (as discussed above). If this transition is detected, line 307a leads to matching step 300. However, if the answer to the transition step 306 is in the negative, line 307b leads back to step 282 to
10 restart the reporting process for the waste disposal container at close proximity to the base module 22. One of skill in the art will know that the color of the LEDs 174a-174c in the above-described embodiment may be varied according to one's desires and tastes. These descriptions are merely a sample of one of the
15 preferred embodiments of the disclosed invention.

[0078] Referring to FIG. 6C, matching step 300 is shown to indicate the position where FIGS. 6A-6B leave off and where FIG. 6C begins. After telephone number is matched with the appropriate condition by step 300, step 308 sends the information
20 comprising the matching telephone number to step 310, which detects whether the telephone line 146 is on-hook (not in use) or off-hook (in use), discussed *infra* and shown in more detail in a block diagram in FIG. 7. Step 312 is the decision step that determines whether the telephone line 146 is on- or off-hook.

If the telephone line **146** is off-hook, the answer to step **312** is in the negative and line **313a** indicates that step **310** is revisited to repeat the off-hook detection. But, if step **312** determines that the telephone line **146** is on-hook, the answer to
5 step **312** is positive and line **313b** shows that the process proceeds to step **314** to call the matched telephone number. Once the telephone number is called, step **316** conveys the information by way of having an originating telephone number that step **318** identifies. Once the originating telephone number has been
10 identified, step **320** disconnects the call. Step **320** most preferably disconnects the call after the fourth ring, or another set time period. All that is required is that the appropriate phone number is identified, which can be done before the call is completed. Thus, the call need not be answered. Thereafter,
15 either one of steps **322** or **324** may take place depending on whether the waste disposal container needs to be emptied (step **322**) or one of the first **50** or second **98** power sources needs to be recharged or changed (step **324**).

[0079] Additionally, it should be noted that after the call
20 is disconnect by step **320**, the base module **22** prepares to receive information from the transmitting module **18** (step **258** in FIG. 6A) and to report the conditions of the trash container located close to the base module **22** (step **282** in FIG. 6B) and the power level of the second power source **98** (step **284** in FIG. 6B).

[0080] When the telephone line **146** of the base module **22** is not in use (on-hook), the modem **142** of the conveying means **134** will successfully be able to call the selected telephone number. But, if the telephone line **146** is already being used, or off-
5 hook, the modem **142** will not be able to make a call on that line **146**. The problem of not knowing whether the telephone line **146** is on-hook or off-hook is solved by an off-hook detecting means **348** that is illustrated in a block diagram in FIG. 7. Referring to FIG. 7, the off-hook detecting means **348** detects when the
10 telephone line **146** is in use and sends the off-hook information to the first microprocessor **86**, which does not allow the modem **142** to call the selected telephone number. Likewise, the off-hook detecting means **348** also detects when the telephone line **146** is on-hook and, thereby, sends this information to the first
15 microprocessor **86** to allow the modem **142** to make the call.

[0081] The preferred off-hook detecting means **348** comprises a plurality of diodes **350** connected to the telephone lines **146** leading, at one end, to a telephone jack **148** and, at another end, to a plurality of discrete circuits **352**. The discrete circuits
20 **352** lead to an opto-isolator IC (opto-coupler IC) **354** that provides the first microprocessor **86** with the on-hook and off-hook information. In a preferred embodiment of the off-hook detecting means **348** as shown in FIG. 7, the preferred diodes **350** comprise four diodes **350a-350d** in a full wave bridge

configuration. The diodes **350a-350d** generate positive (+) and negative (-) voltage changes, whereby a positive voltage change represents that the telephone line **146** is on-hook and a negative voltage change represents that the telephone line **146** is off-hook. The preferred discrete circuits **352** comprise a first discrete circuit **352a** and a second discrete circuit **352b**, whereby the first discrete circuit **352a** detects the positive or negative voltage change from the diodes **350a-350d** and relays that information to the second discrete circuit **352b**. The second discrete circuit **352b**, then, becomes activated and further relays the on-hook/off-hook information to the opto-isolator IC **354**. The opto-isolator IC **354** preferably comprises an LED **357** and a phototransistor **358**. The LED **357** is lit when the telephone line **146** is off-hook and dim when on-hook. Once the information passes through the LED **357**, it is sent to the phototransistor **358** that is light-activated and relays the information from the LED **174** to the first microprocessor **86**. The first microprocessor **86** will, therefore, be informed as to whether the telephone line **146** is on- or off-hook.

20 **[0082]** This invention has great utility in the waste disposal industry, but it may also be useful in other industries where remote containers or locations need to be monitored. Hence, while the invention has been described in connection with a preferred embodiment, it will be understood that it is not

intended that the invention be limited to that embodiment. On the contrary, it is intended to cover all alternatives, modifications and equivalents as may be included within the spirit and scope of the invention as disclosed.

5 [0083] As to the manner of usage and operation of the instant invention, same should be apparent from the above disclosure, and accordingly no further discussion relevant to the manner of usage and operation of the instant invention shall be provided.

[0084] With respect to the above description then, it is to
10 be realized that the optimum dimensional relationships for the parts of the invention, to include variations in size, materials, shape, form, function and manner of operation, assembly and use, are deemed readily apparent and obvious to one skilled in the art, and all equivalent relationships to those illustrated in the
15 drawings and described in the specification are intended to be encompassed by the present invention.

[0085] Therefore, the foregoing is considered illustrative of only the principles of the invention. Further, since numerous modifications and changes will readily occur to those skilled in
20 the art, it is not desired to limit the invention to the exact construction and operation shown and described, and accordingly, all suitable modifications and equivalents may be resorted to, falling within the scope of the invention.